

Aufbau interaktiver 3D- Engines

Universität Osnabrück
Fachbereich Mathematik / Informatik

4. Übung

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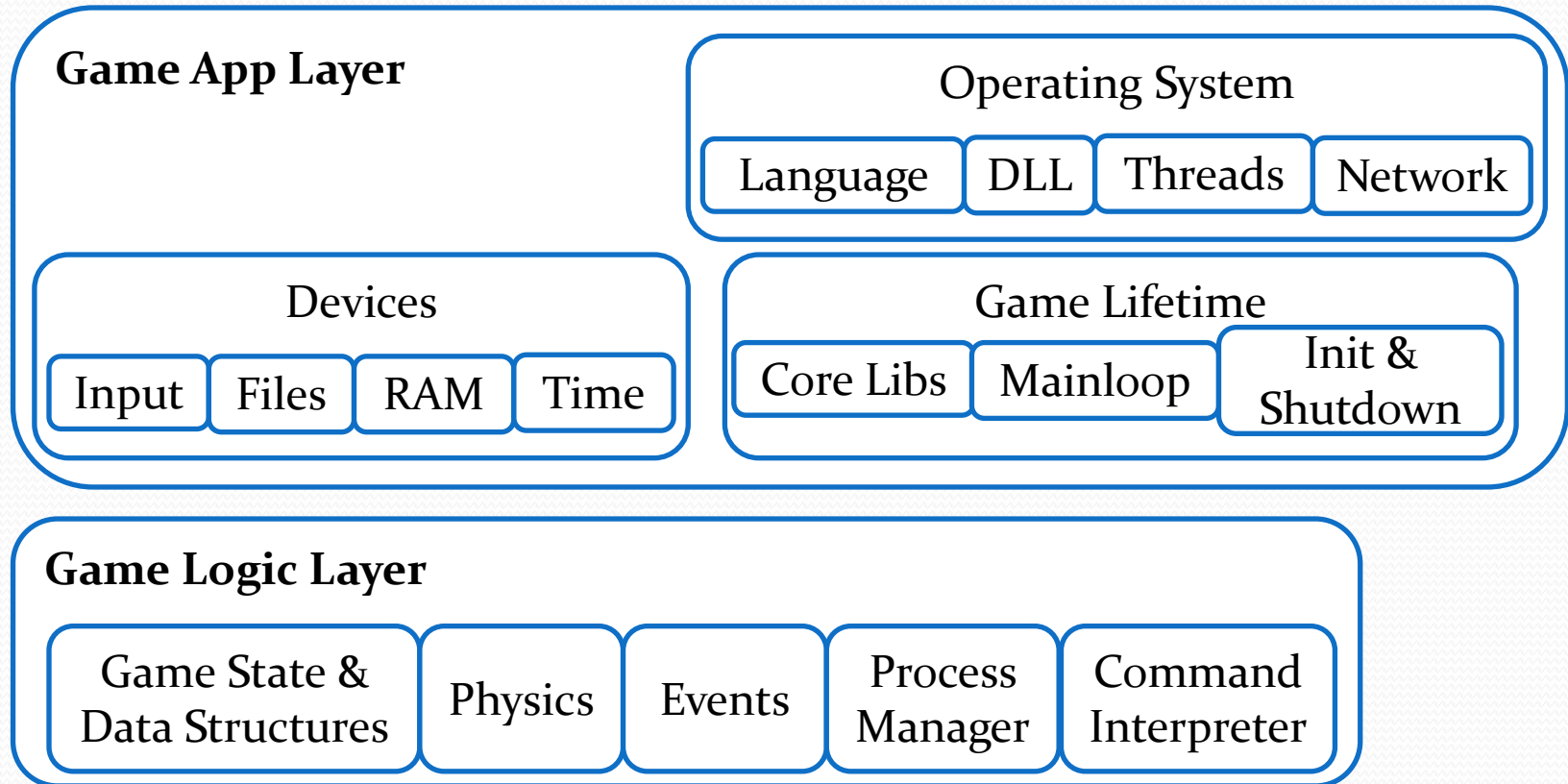
30.04.2013

Übersicht

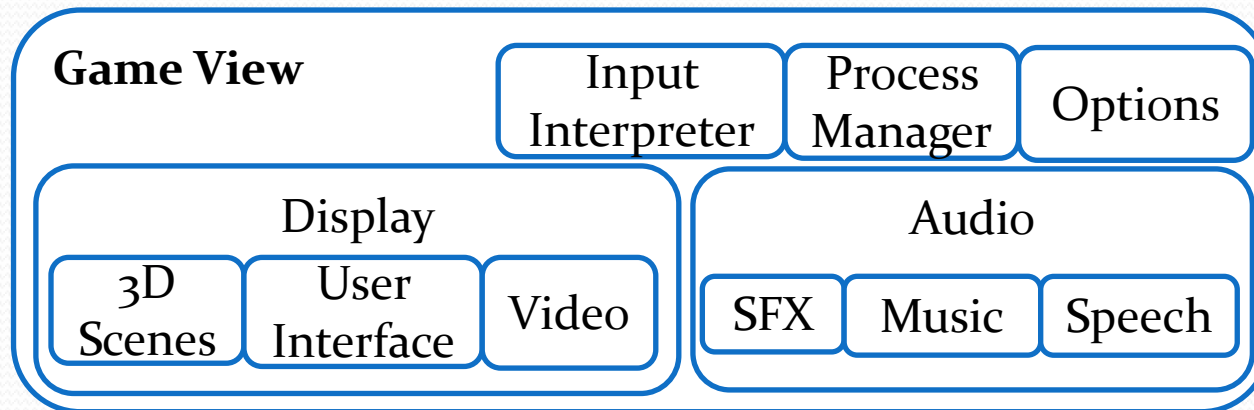
1. Fragen zum aktuellen Übungsblatt
2. Rückblick: Übersicht
3. Implementationsdetails
 1. Eventsystem
 2. Prozesssystem
 3. Input
4. Mathematische Grundlagen

Fragen zum aktuellen Übungsblatt

Rückblick: Übersicht



Rückblick: Übersicht



Quelle: Game Coding Complete

Implementation: EventSystem

- Eventmanager
 - Verwaltung der Event Queues und der Listener
 - Events werden gesammelt und verarbeitet
- Eventlistener
 - Implementieren die `trigger(Eventdata data)` Funktion
- Events
 - Haben eine eindeutige ID
 - Transportieren spezielle Informationen

Implementation: EventManager

```
private List<EventData> currentEvents = new LinkedList<>();
private List<EventData> nextEvents = new LinkedList<>();
private final Map<Integer, List<EventListener>> listeners = new HashMap<>();
```

```
public boolean register(EventListener listener, int... types) {
    boolean success = true;
    for(int type : types) {
        List<EventListener> list = this.listeners.get(type);
        if(list == null) {
            this.listeners.put(type, list = new LinkedList<>());
        }
        if(list.contains(listener)) {
            Logger.INSTANCE.warning("Don't register listener twice.");
            success = false;
        } else {
            list.add(listener);
        }
    }
    return success;
}
```

```
public void queueEvent(EventData event) {
    event.timeStamp = GameApp.getRealTimer().getTimeStamp();
    this.currentEvents.add(event);
}
```

Implementation: EventManager

```
public void processEvents() {
    List<EventData> toProcess = this.currentEvents;
    this.currentEvents = this.nextEvents;
    for (EventData event : toProcess) {
        List<EventListener> list = this.listeners.get(event.getId());
        if(list != null) {
            for(EventListener listener : list) {
                listener.trigger(event);
            }
        }
    }
    toProcess.clear();
    this.nextEvents = toProcess;
}
```


Implementation: Events und Listener

```
public static class ChatMessageEvent extends EventData {
    public static final int ID = 0x1a40c664;

    public final String message;
    public final String channel;

    public ChatMessageEvent(String message, String channel) {
        this.message = message;
        this.channel = channel;
    }

    @Override
    public int getId() {
        return ID;
    }
}
```

```
public class TestListener implements EventListener {
    public void trigger(EventData data) {
        if(data.getId() == ActorCreatedEvent.ID) {
            ...
        }
    }
}
```

Implementation: Prozesssystem

- Prozess
 - Besitzt zeitliche Ausdehnung
 - Kann erfolgreich sein, oder fehlschlagen
 - Kann pausiert oder abgebrochen werden
- Prozessmanager
 - Verwaltet Prozesse
 - Prozesse führen über einen, oder nach einem Zeitraum Operationen durch

Implementation: Prozess

```
static enum State {  
    UNINITIALIZED,  
    REMOVED,  
    RUNNING,  
    PAUSED,  
    SUCCEEDED,  
    FAILED,  
    ABORTED,  
}  
  
private State state = State.UNINITIALIZED;  
  
private EngineProcess child = null;
```

```
protected abstract void onUpdate(long dMillis);  
  
public final void succeed() {  
    if(this.isAlive()) {  
        this.state = State.SUCCEEDED;  
    }  
}  
  
protected void onSuccess() {}
```

Implementation: ProzessManager

```
private final LinkedList<EngineProcess> processes = new LinkedList<>();  
private final List<EngineProcess> tempProcesses = new LinkedList<>();
```

```
public int update(long deltaMillis) {  
    this.processes.addAll(this.tempProcesses); this.tempProcesses.clear();  
    ListIterator<EngineProcess> iter = this.processes.listIterator();  
    for(EngineProcess process; iter.hasNext();) {  
        process = iter.next();  
        if(process.getState() == EngineProcess.State.UNINITIALIZED) {  
            process.onInit();  
        } else if(process.getState() == EngineProcess.State.RUNNING) {  
            process.onUpdate(deltaMillis);  
        } else if(process.isDead()) {  
            switch(process.getState()) {  
                case ABORTED:  
                    process.onAbort();  
                    iter.remove(); ++failed; break;  
                case FAILED:  
                    process.onFail();  
                    iter.remove(); ++failed; break;  
                case SUCCEEDED:  
                    process.onSuccess();  
                    if(process.getChild() != null) {  
                        iter.set(process.getChild());  
                    } else {  
                        iter.remove();  
                        ++succeeded; } break;  
            }  
        }  
    }  
    return (failed << 16) | succeeded;  
}
```

Implementation: Input

- InputHandler (GameApp)
 - Leitet Hardware-Input an registrierte Handler weiter
- KeyboardHandler
 - **onKeyDown**, **onKeyUp** und **isProcessingRepeatEvents** verarbeiten Tastatur-Input
- PointerHandler
 - **pointerMoved**, **onButtonDown** , **onButtonUp** und **onWheelMoved** verarbeiten Maus-Input
- PlayerControls (implements KeyboardHandler, PointerHandler)
 - Standard-InputHandler, der Eingaben in Events umwandelt

Implementation: InputHandler

```
private final LinkedList<KeyboardHandler> keyboardHandlers = new LinkedList<>();  
private final LinkedList<PointerHandler> pointerHandlers = new LinkedList<>();
```

```
public void processInput() {  
    while(Keyboard.next()) {  
        boolean processed = false; boolean down = Keyboard.getEventKeyState();  
        Iterator<KeyboardHandler> iter = this.keyboardHandlers.iterator();  
        while(!processed && iter.hasNext()) {  
            KeyboardHandler handler = iter.next();  
            if(down) {  
                if(!Keyboard.isRepeatEvent() || handler.isProcessingRepeatEvents()) {  
                    processed = handler.onKeyDown(Keyboard.getEventKey(), Keyboard.getEventCharacter());  
                }  
            } else {  
                processed = handler.onKeyUp(Keyboard.getEventKey());  
            }  
        }  
    }  
    while(Mouse.next()) {  
        boolean processed = false; int button = Mouse.getEventButton();  
        boolean down = Mouse.getEventButtonState(); int wheel = Mouse.getEventDWheel();  
        int posX = Mouse.getEventX(), posY = Mouse.getEventY(), dX = Mouse.getEventDX(), dY = Mouse.getEventDY();  
        Iterator<PointerHandler> iter = this.pointerHandlers.iterator();  
        while(!processed && iter.hasNext()) {  
            if(button == -1 && (dX != 0 || dY != 0)) {  
                processed = iter.next().pointerMoved(posX, posY, dX, dY);  
            } else if(wheel != 0) {  
                processed = iter.next().onWheelMoved(wheel);  
            } else if(down) {  
                processed = iter.next().onButtonDown(button);  
            } else {  
                processed = iter.next().onButtonUp(button);  
            }  
        }  
    }  
}
```

Implementation: PlayerControls

```
private final Joiner<Integer, Class<EventData>> keyMappings = new Joiner<>();  
private final Joiner<Integer, Class<EventData>> btnMappings = new Joiner<>();  
private Class<EventData> pointerMovedEvt;  
private Class<EventData> pointerWheelEvt;
```

```
private boolean initFromConfigSection(String sectionName)
```

```
public boolean onKeyDown(int key, char c) {  
    Class<EventData> evtClass = this.keyMappings.getJoined1(key);  
    return evtClass != null && this.fireInputEvent(evtClass, true);  
}  
  
public boolean pointerMoved(int posX, int posY, int dX, int dY) {  
    if(this.pointerMovedEvt != null) {  
        try {  
            EventData evt = this.pointerMovedEvt.newInstance();  
            if(evt instanceof PointerMovedEvent) {  
                ((PointerMovedEvent)evt).setDelta(dX, dY);  
            }  
            GameApp.getEventManager().queueEvent(evt);  
        } catch (InstantiationException | IllegalAccessException ex) {  
            Logger.INSTANCE.error(ex.getMessage());  
        }  
        return true;  
    } else {  
        return false;  
    }  
}
```

Mathematische Grundlagen

- $S\left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right) = \begin{pmatrix} \frac{1}{2} & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

- $T_x(0,5) = \begin{pmatrix} 1 & 0 & 0 & 0,5 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

Mathematische Grundlagen

- $R_x\left(\pm\frac{\pi}{4}\right) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\pm\frac{\pi}{4} & -\sin\pm\frac{\pi}{4} & 0 \\ 0 & \sin\pm\frac{\pi}{4} & \cos\pm\frac{\pi}{4} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

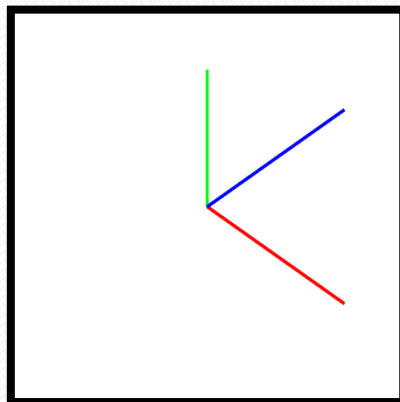
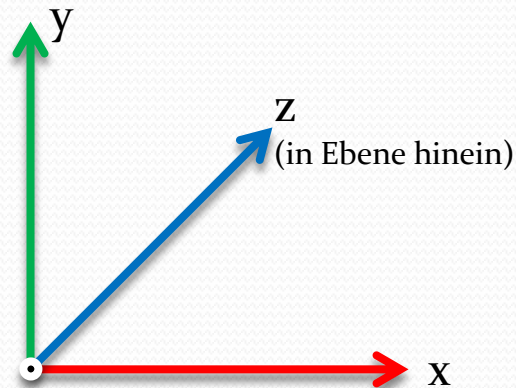
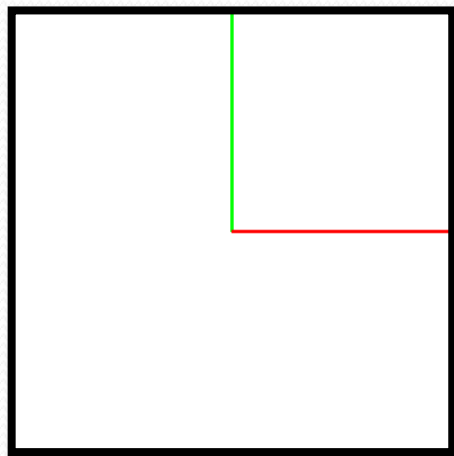
- $R_y\left(\pm\frac{\pi}{4}\right) = \begin{pmatrix} \cos\pm\frac{\pi}{4} & 0 & \sin\pm\frac{\pi}{4} & 0 \\ 0 & 1 & 0 & 0 \\ -\sin\pm\frac{\pi}{4} & 0 & \cos\pm\frac{\pi}{4} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

- $R_z\left(\pm\frac{\pi}{4}\right) = \begin{pmatrix} \cos\pm\frac{\pi}{4} & -\sin\pm\frac{\pi}{4} & 0 & 0 \\ \sin\pm\frac{\pi}{4} & \cos\pm\frac{\pi}{4} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

- $\sin\left(\pm\frac{\pi}{4}\right) = \pm\frac{1}{\sqrt{2}} = \cos\left(\pm\frac{\pi}{4}\right)$

Mathematische Grundlagen

- Ausgangslage

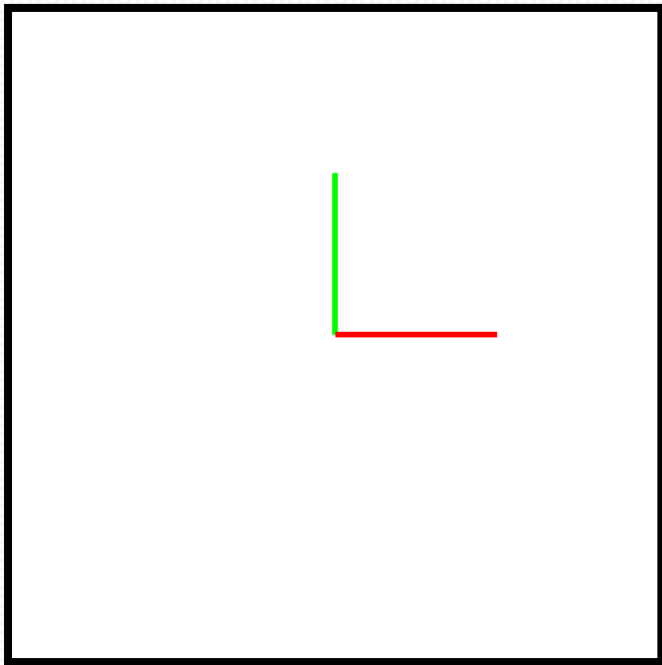


$$M = R_x\left(-\frac{\pi}{4}\right) * R_y\left(+\frac{\pi}{4}\right)$$

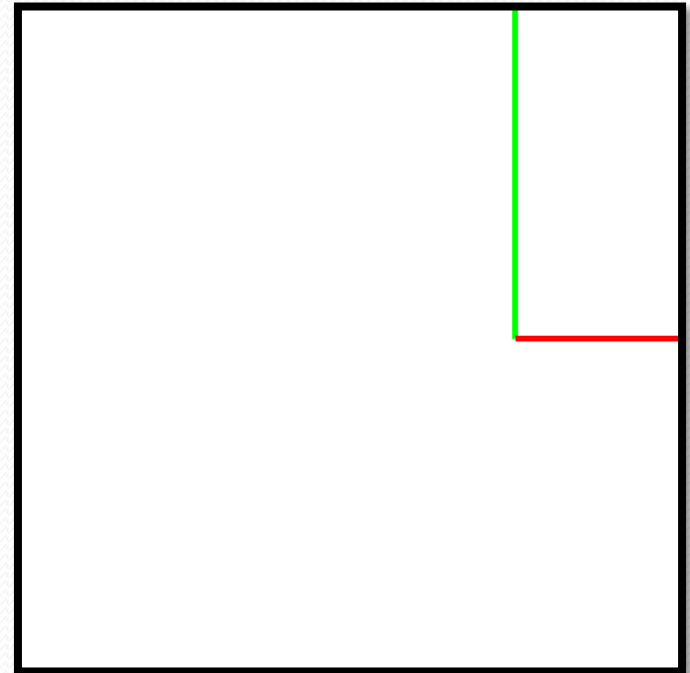
*Merke:
Positive Rotationen gehen
gegen den Uhrzeigersinn, wenn
man entlang der Achse sieht*

Mathematische Grundlagen

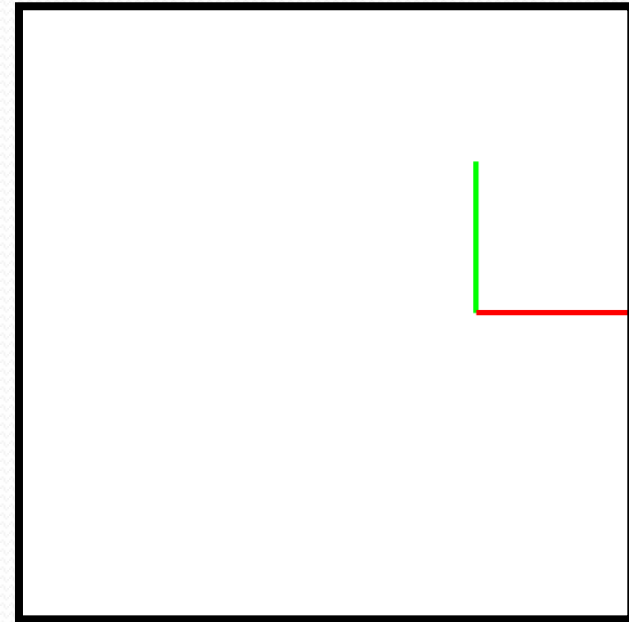
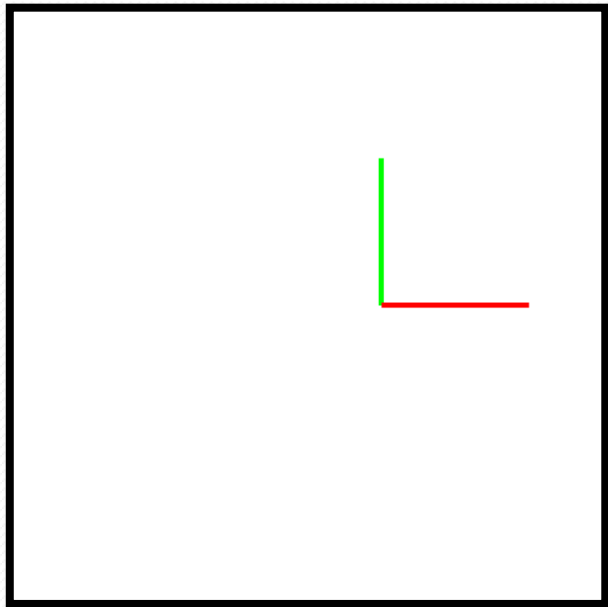
$$M = S\left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right)$$



$$M = T_x\left(\frac{1}{2}\right)$$



Mathematische Grundlagen

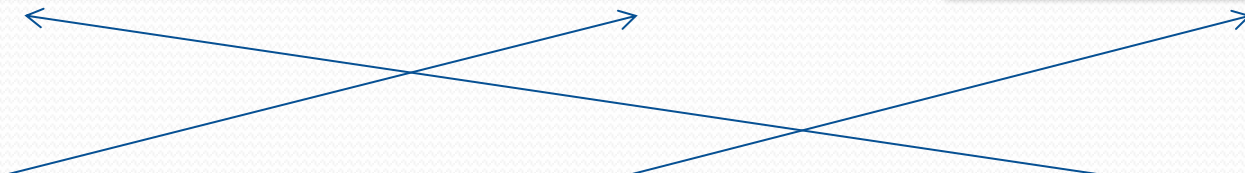
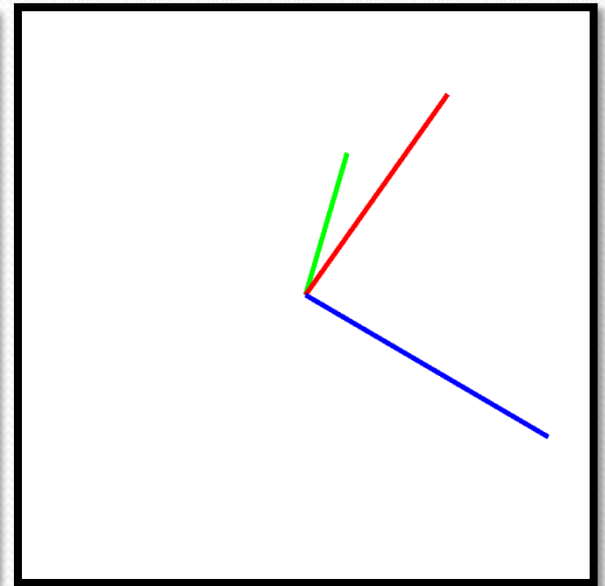
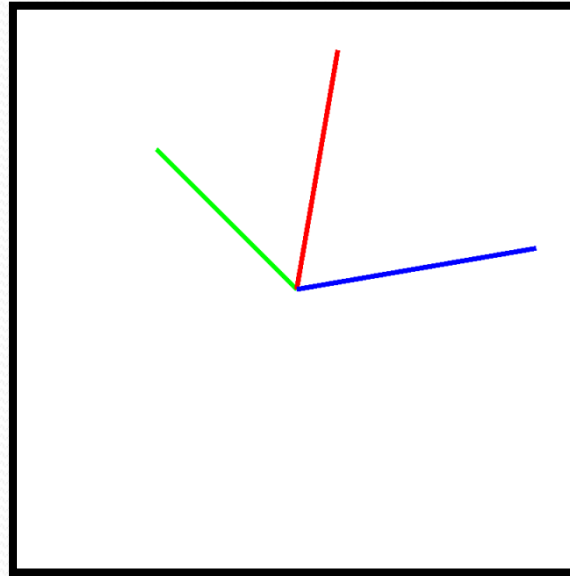
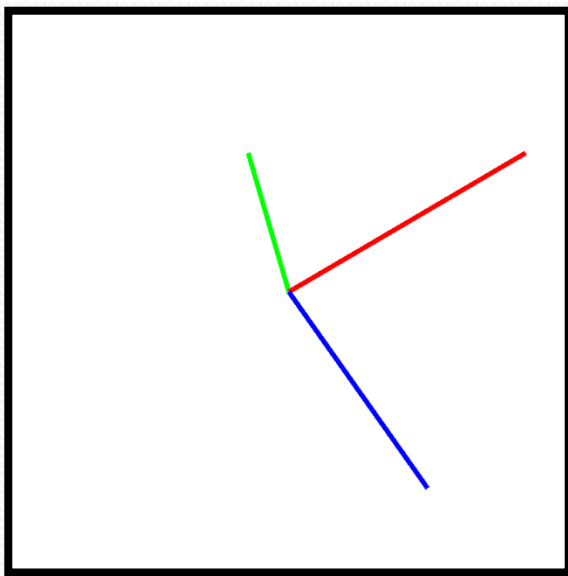


$$M = S\left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right) * T_x\left(\frac{1}{2}\right)$$

$$M = T_x\left(\frac{1}{2}\right) * S\left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right)$$

*Merke:
Skalierungen wirken global*

Mathematische Grundlagen



$$M = R_x\left(\frac{\pi}{4}\right) * R_z\left(\frac{\pi}{4}\right) * R_y\left(\frac{\pi}{4}\right) \quad M = R_y\left(\frac{\pi}{4}\right) * R_z\left(\frac{\pi}{4}\right) * R_x\left(\frac{\pi}{4}\right) \quad M = R_y\left(\frac{\pi}{4}\right)$$

Merke: $* R_x\left(\frac{\pi}{4}\right) * R_z\left(\frac{\pi}{4}\right)$
 Yaw (Y) * Pitch (X) * Roll (Z) ₂₁

Mathematische Grundlagen

Merke:

*$M = \text{Translation} * \text{Rotation} * \text{Skalierung}$*

Nächste Woche:

- Abgabe des aktuellen Übungsblattes
- Ausgabe des nächsten Übungsblattes

**Vielen Dank für die
Aufmerksamkeit 😊**