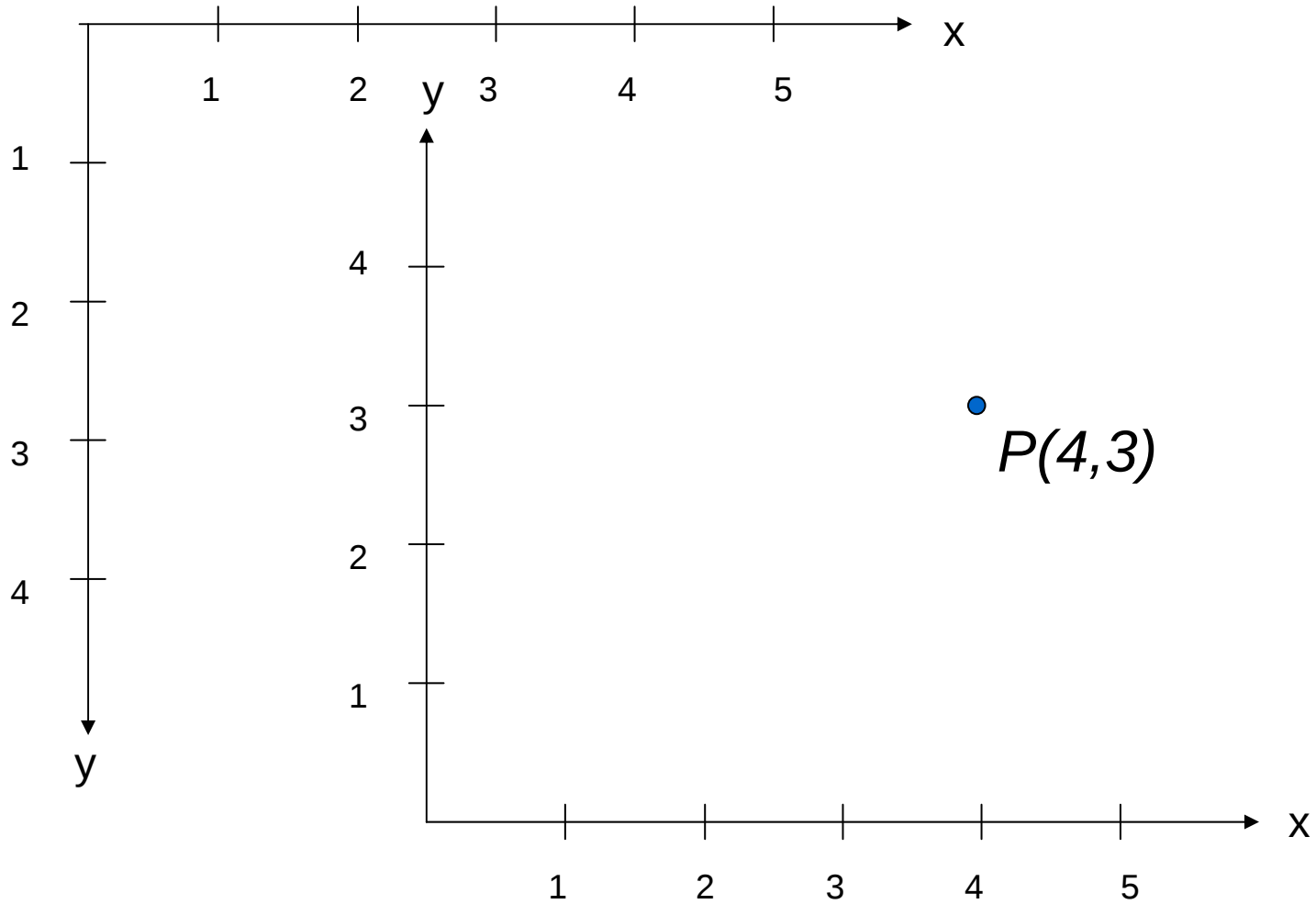
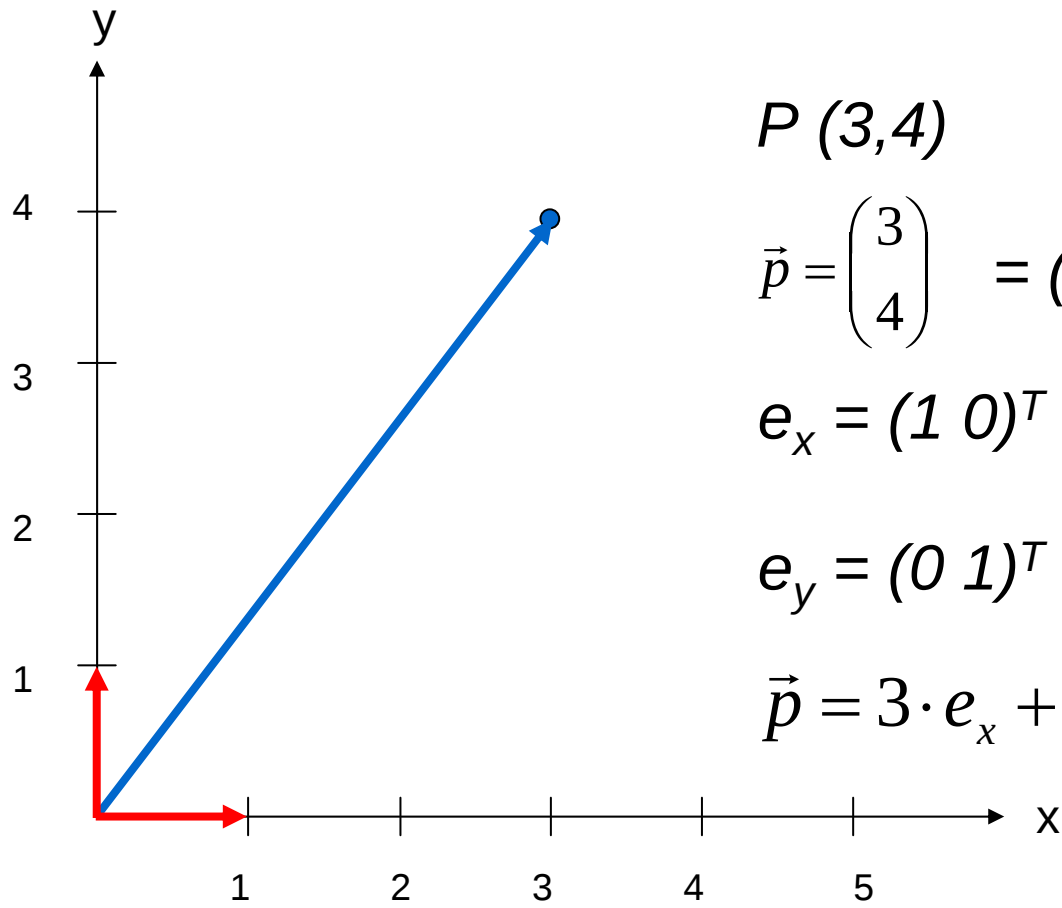


Kapitel 3: 2D-Grundlagen

Koordinatensysteme



Punkt + Vektor



$$P(3,4)$$

$$\vec{p} = \begin{pmatrix} 3 \\ 4 \end{pmatrix} = (3 \ 4)^T$$

$$e_x = (1 \ 0)^T$$

$$e_y = (0 \ 1)^T$$

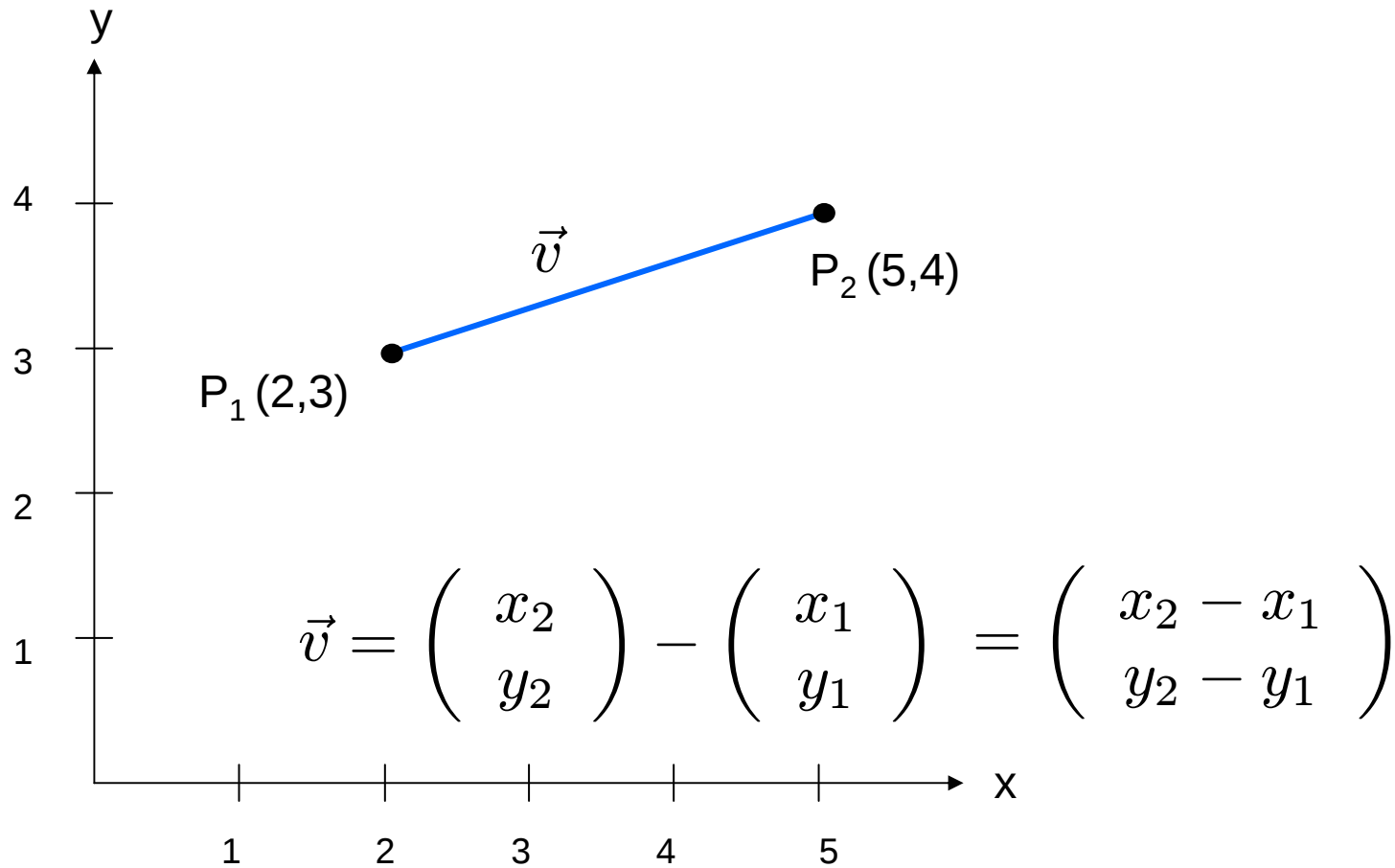
$$\vec{p} = 3 \cdot e_x + 4 \cdot e_y$$

`setPixel(int x, int y)`

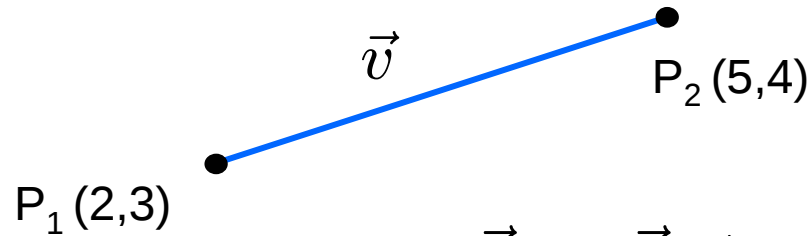
`setPixel(3, 4);`

`setPixel((int)(x+0.5), (int)(y+0.5));`

Linie



Parametrisierte Gradengleichung



$$g : \vec{u} = \vec{p}_1 + r \cdot \vec{v}; \quad r \in \mathbb{R}$$

$$l : \vec{u} = \vec{p}_1 + r \cdot \vec{v}; \quad r \in [0; 1]$$

$$d = \|\overline{P_1 P_2}\| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

VectorLine

```
int  x1,y1,x2,y2,x,y,dx,dy;
double r, step;

dy = y2-y1;
dx = x2-x1;

step = 1.0/Math.sqrt(dx*dx+dy*dy);
for (r=0.0; r <= 1; r=r+step) {
    x = (int)(x1+r*dx+0.5);
    y = (int)(y1+r*dy+0.5);
    setPixel(x,y);
}
```

Gradengleichung als Funktion

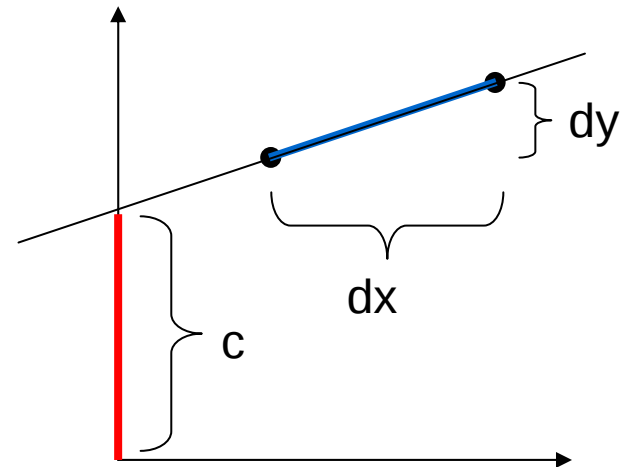
$$y = f(x) = s \cdot x + c$$

$$s = \frac{y_2 - y_1}{x_2 - x_1}$$

$$\frac{y_1 - c}{x_1 - 0} = \frac{y_2 - y_1}{x_2 - x_1}$$

$$c = \frac{y_1 \cdot x_2 - y_2 \cdot x_1}{x_2 - x_1}$$

$$y = \frac{y_2 - y_1}{x_2 - x_1} \cdot x + \frac{x_2 \cdot y_1 - x_1 \cdot y_2}{x_2 - x_1}$$



StraightLine

von links nach rechts

```
s = (double)(y2-y1)/(double)(x2-x1);  
c = (double)(x2*y1-x1*y2)/(double)(x2-x1);  
  
for (x=x1; x <= x2; x++) {  
    y = (int)(s*x+c+0.5);  
    setPixel(x,y);  
}
```

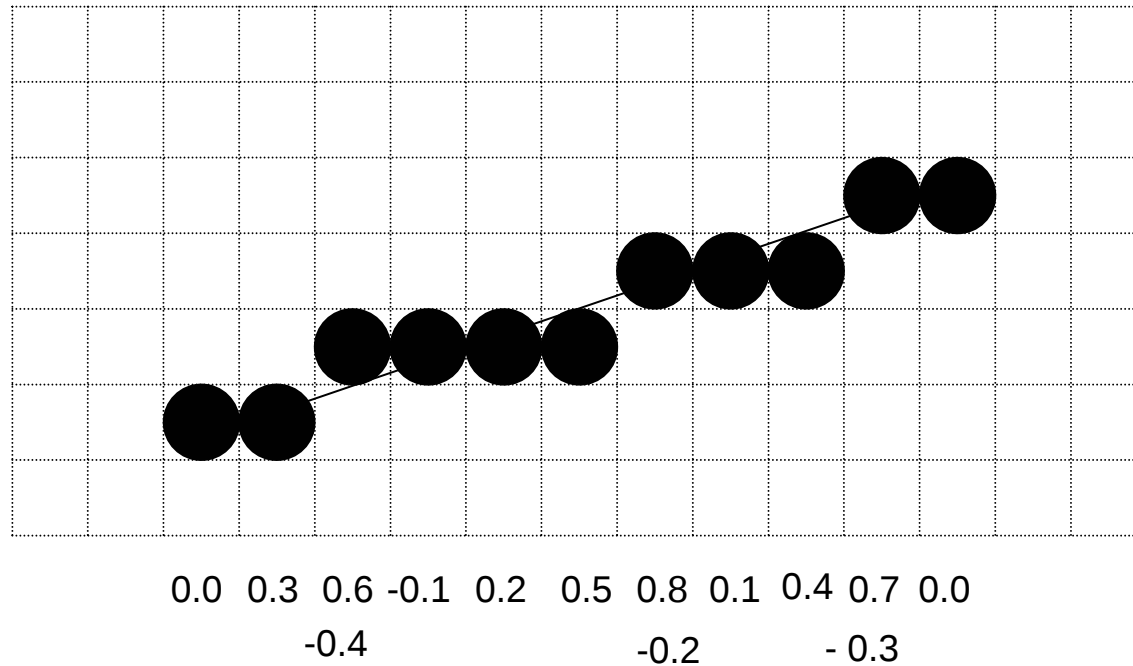
Oktanden

1.

Bresenham

Steigung $s = \Delta y / \Delta x = 3/10 = 0.3$

Fehler $error = y_{ideal} - y_{real}$



BresenhamLine, die 1.

```
s = (double)(y2-y1)/(double)(x2-x1);
error = 0.0;
x = x1;
y = y1;
while (x <= x2){
    setPixel(x,y);
    x++;
    error = error + s;
    if (error > 0.5) {
        y++;
        error = error - 1.0;
    }
}
```

Integer-Arithmetik

Mache Steigung + Fehler ganzzahlig:

$$s_{neu} = s_{alt} \cdot 2dx = \frac{dy}{dx} \cdot 2dx = 2dy$$

BresenhamLine, die 2.

```
delta = 2*(y2-y1);  
error = 0.0;  
x = x1;  
y = y1;  
while (x <= x2){  
    setPixel(x,y);  
    x++;  
    error = error + delta;  
    if (error > (x2-x1) {  
        y++;  
        error = error - 2*dx;  
    }  
}
```

Vergleich mit 0

- vergleiche **error** mit 0,
d.h. verschiebe **error** um $(x_2 - x_1)$ nach unten
- verwende **schr1tt** für $-2 * dx$

BresenhamLine, die 3.

```
delta = 2*(y2-y1);
error = -(x2-x1);
schritt = -2*dx
x = x1;
y = y1;
while (x <= x2){
    setPixel(x,y);
    x++;
    error = error + delta;
    if (error > 0 {
        y++;
        error = error + schritt;
    }
}
```

BresenhamLine

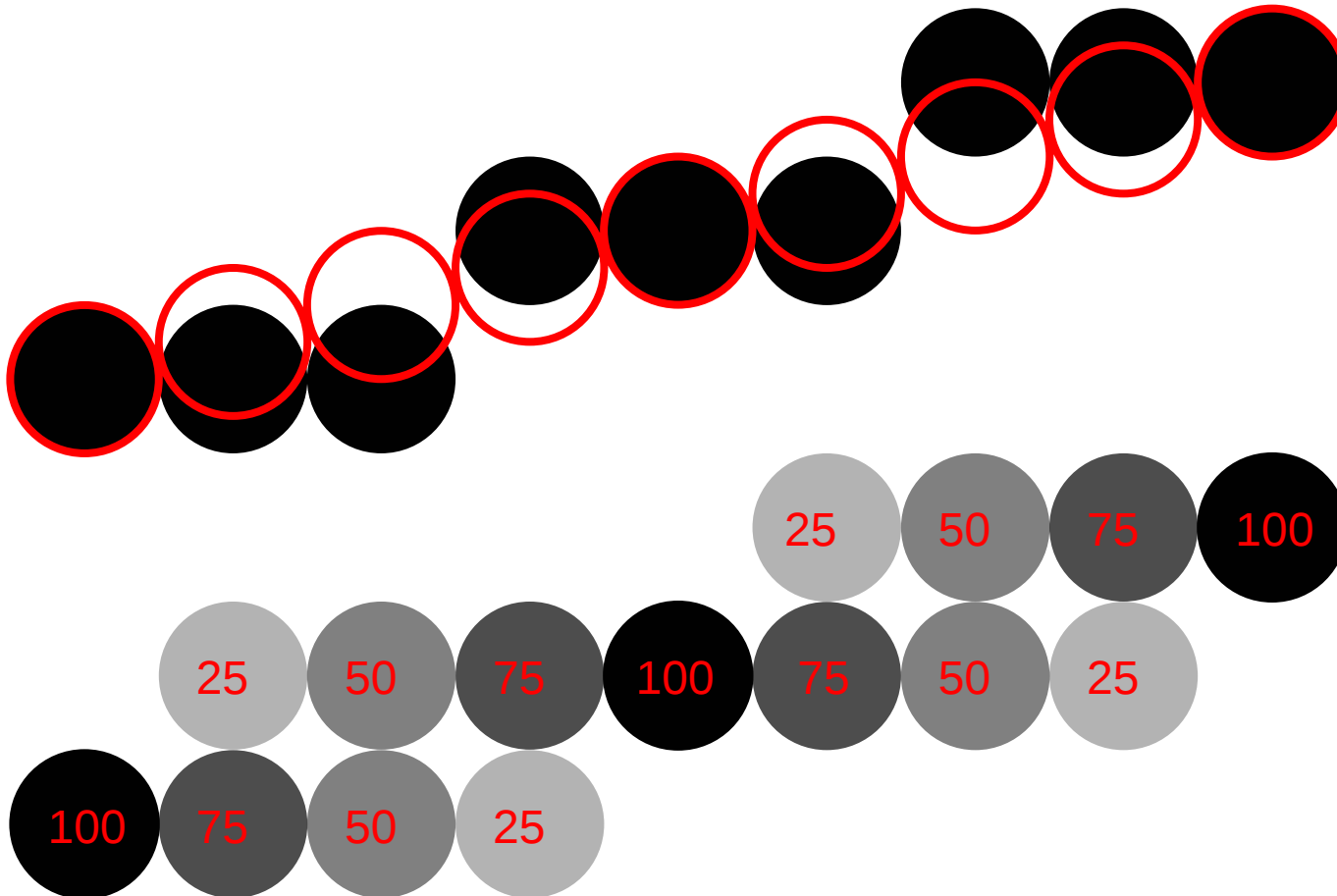
alle 8 Oktanten durch Fallunterscheidung abhandeln:

[~cg/2004/Java/line/BresenhamLine.java](#)

Java-Applet:

[~cg/2004/skript/node46.htm](#)

Antialiasing

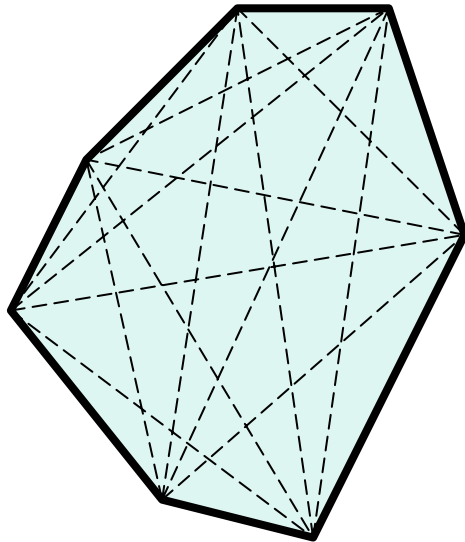


Antialiasing in Adobe Photoshop

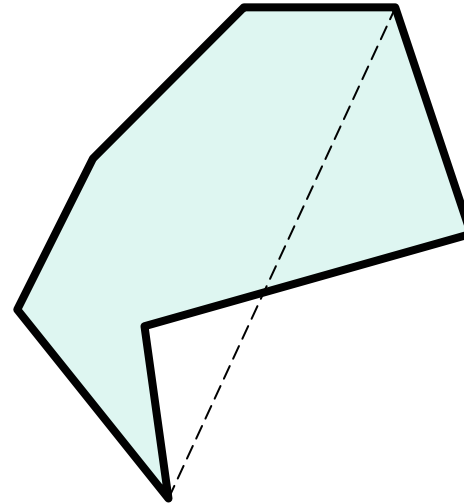


The image displays two rows of the lowercase letters 'a', 'b', and 'c' in a serif typeface. The top row shows the text with antialiasing, where the edges are smooth and the colors transition from black to white through various shades of gray. The bottom row shows the text without antialiasing, resulting in a pixelated appearance with sharp, jagged edges and no intermediate gray tones.

Polygon



konvex



konkav

Punkt versus Gerade

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \end{pmatrix} + r \cdot \begin{pmatrix} 7-2 \\ 5-3 \end{pmatrix}$$

$$x = 2 + 5r$$

$$y = 3 + 2r$$

$$2x = 4 + 10r$$

$$-5y = -15 - 10r$$

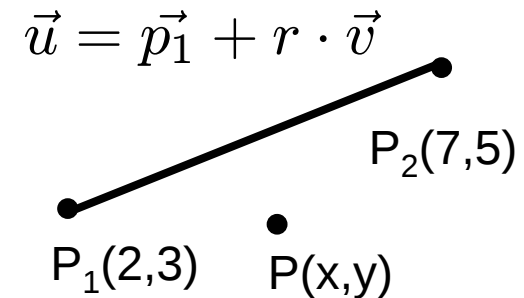
$$2x - 5y = -11$$

$$2x - 5y + 11 = 0$$

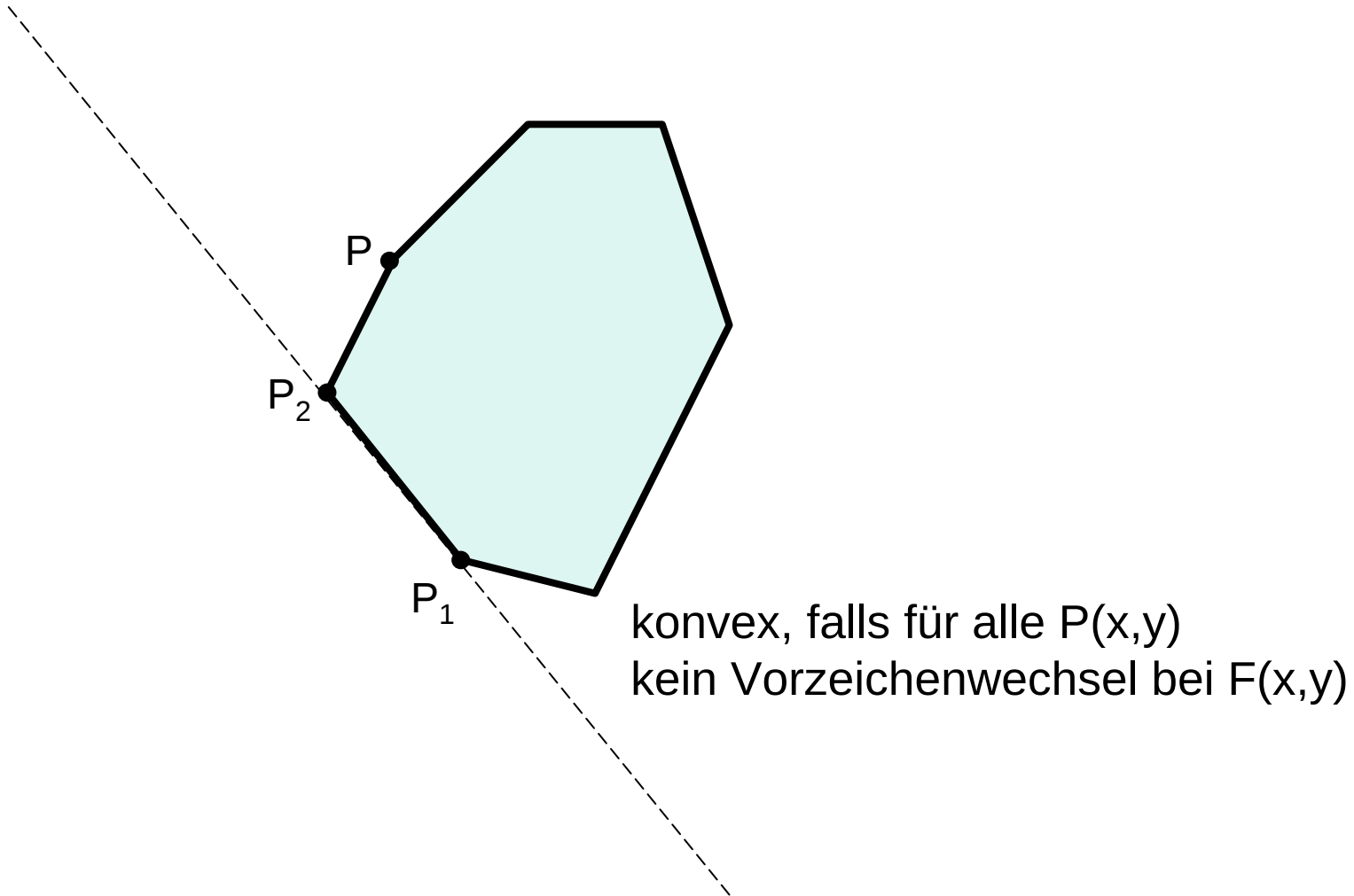
$F(x,y) = 0$ falls P auf der Geraden

< 0 falls P links von der Geraden

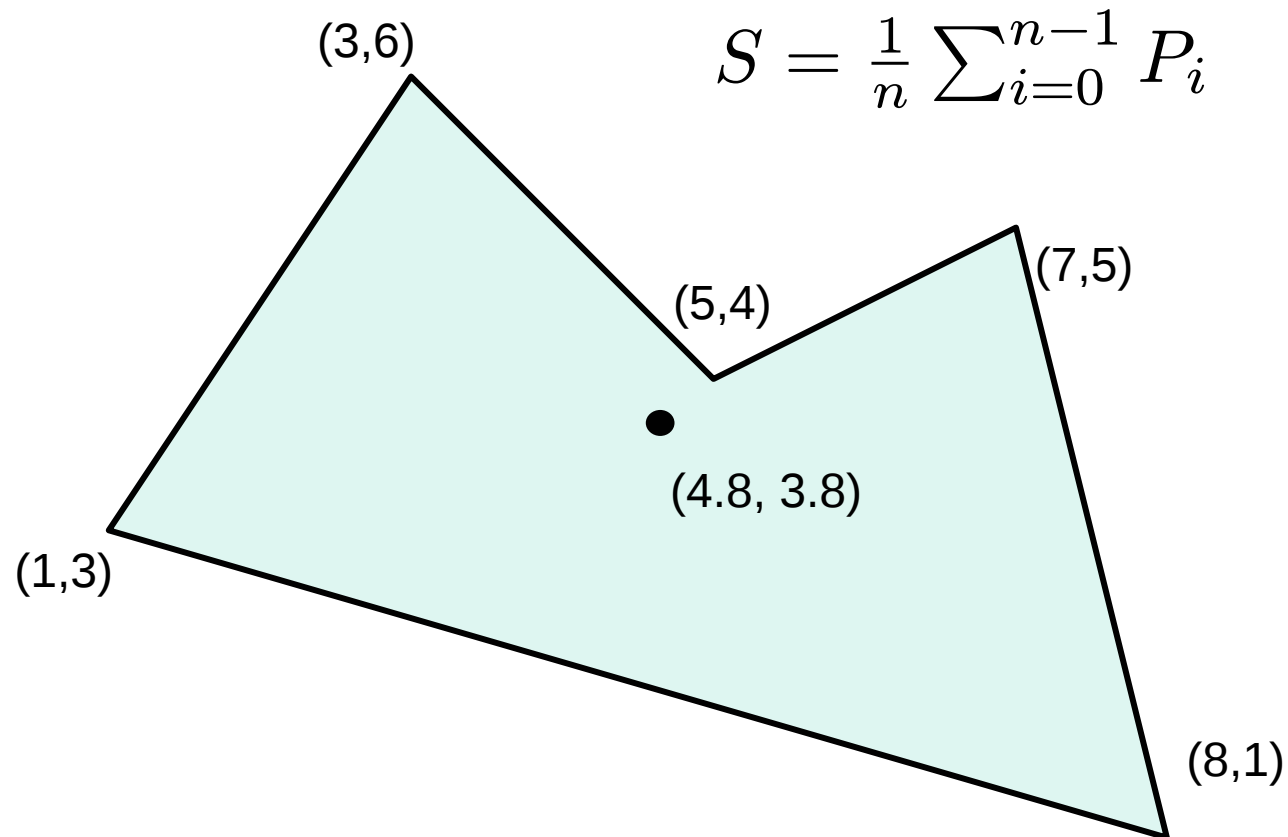
> 0 falls P rechts von der Geraden



Konvexitätstest nach Paul Bourke



Schwerpunkt



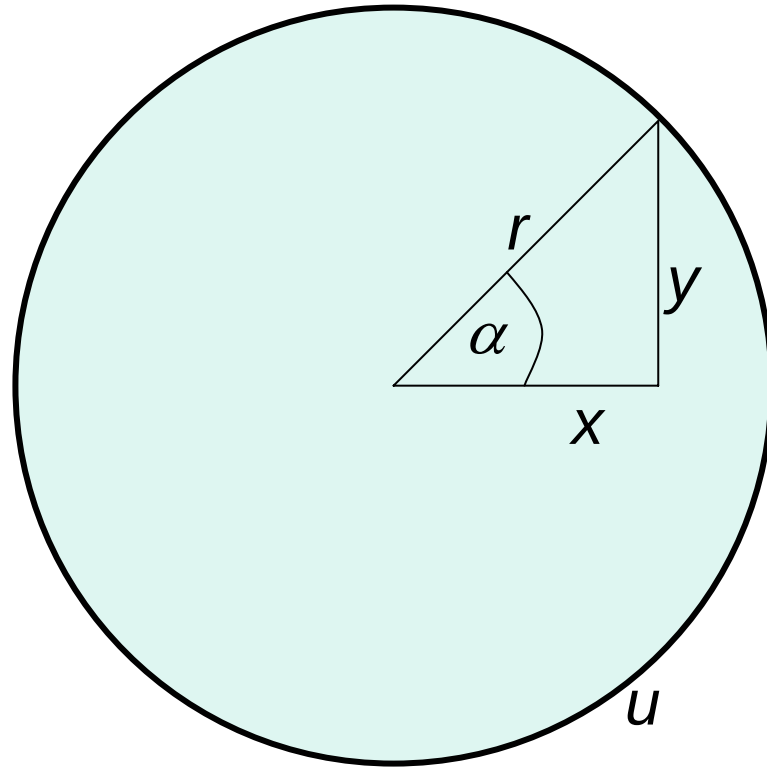
Kreis um (0,0)

$$x = r \cdot \cos(\alpha)$$

$$y = r \cdot \sin(\alpha)$$

$$u = 2 \cdot \pi \cdot r$$

$$\text{step} = 2 \cdot \pi / 2 \cdot \pi \cdot r = 1/r$$



TriCalcCircle

```
double step = 1.0/(double r);  
double winkel;  
  
for (winkel = 0.0;  
     winkel < 2*Math.PI;  
     winkel = winkel+step){  
  
    setPixel((int) r*Math.sin(winkel)+0.5),  
            (int) r*Math.cos(winkel)+0.5));  
}
```

TriTableCircle

```
// Tabellen sin + cos seien berechnet

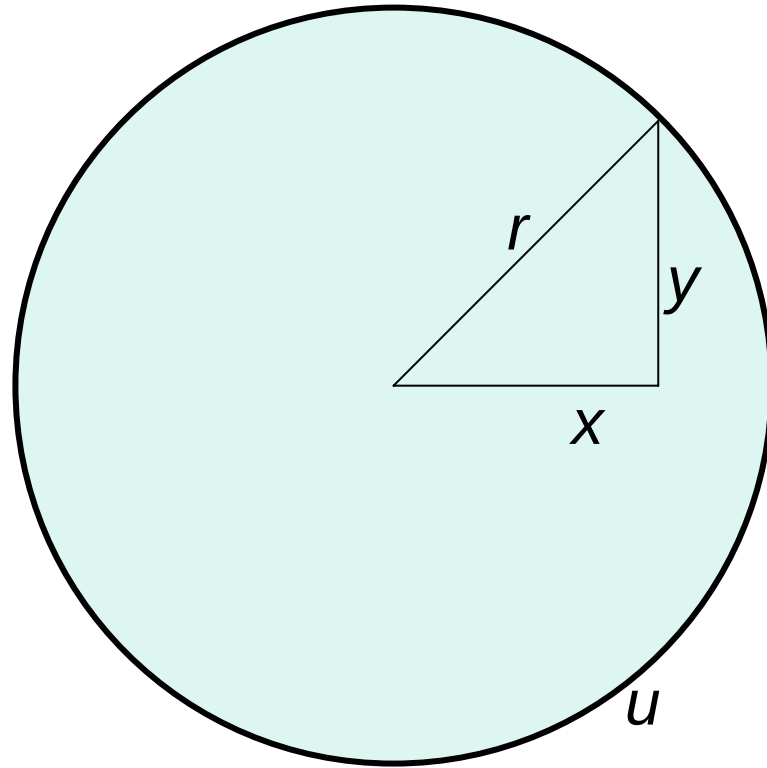
int winkel;

for (winkel = 0;
     winkel < 360;
     winkel++){

    setPixel((int) r*sin[winkel] + 0.5),
             (int) r*cos[winkel] + 0.5));
}
```

Kreis um (0,0)

$$x^2 + y^2 = r^2$$



PythagorasCircle, die 1.

$$y = \sqrt{r^2 - x^2}$$

```
for (x=0; x <=r; x++){  
    y = (int) Math.sqrt(r*r-x*x);  
    setPixel(x,y);  
}
```

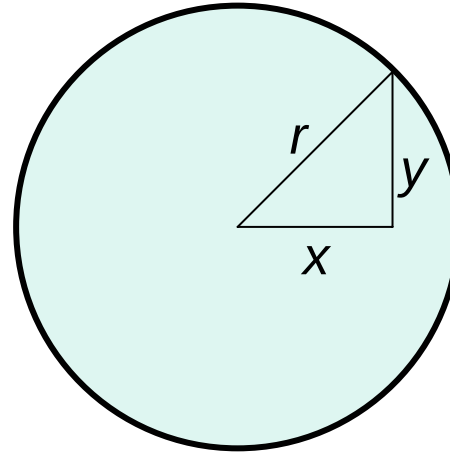
PythagorasCircle, die 2.

$$y = \sqrt{r^2 - x^2}$$

$$w = r^2 - 1, r^2 - 4, r^2 - 9, r^2 - 16, \dots$$

```
d = 1;
for (w=r*r; w >=0; w=w-d){
    y = (int) Math.sqrt(w);
    setPixel(x,y);
    d = d+2;
}
```

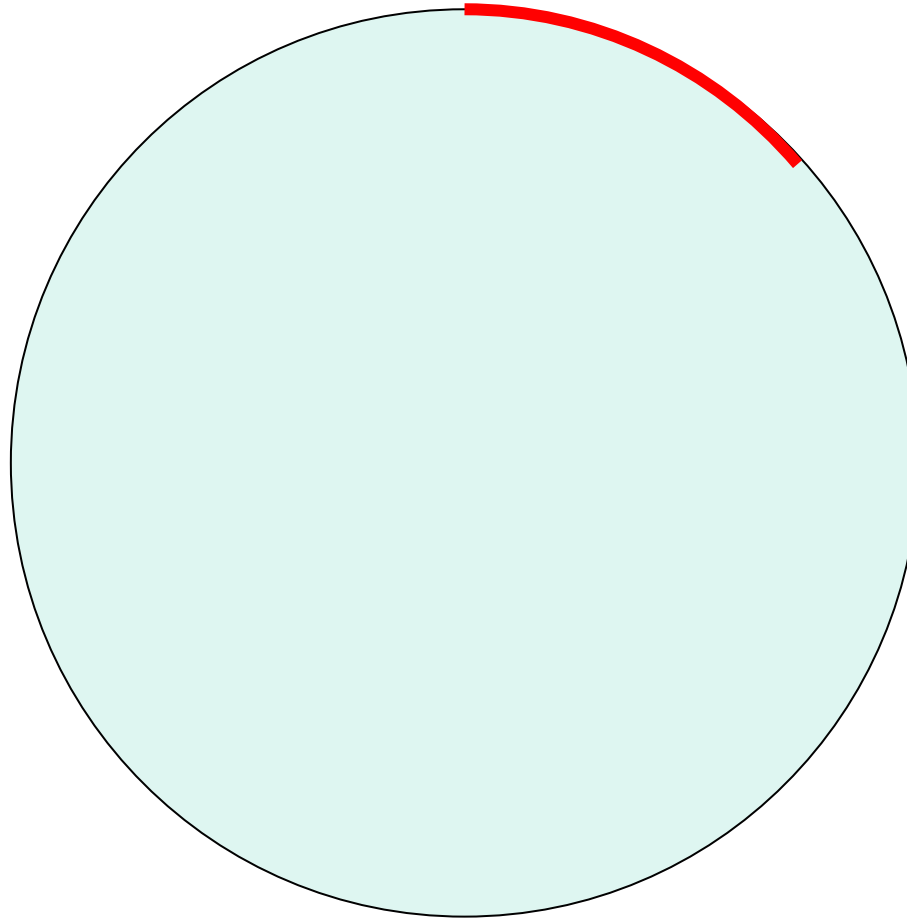
Punkt versus Kreis



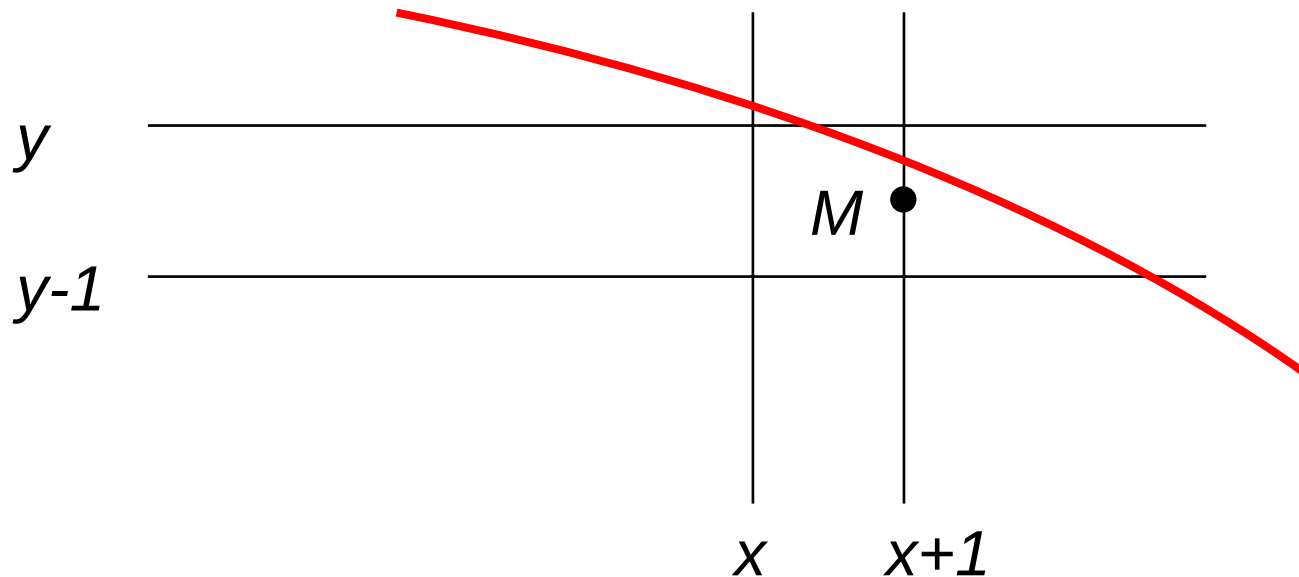
$$F(x,y) = x^2 + y^2 - r^2$$

$F(x,y) = 0$ für (x,y) auf dem Kreis
 < 0 für (x,y) innerhalb des Kreises
 > 0 für (x,y) außerhalb des Kreises

Kreis im 2. Oktanten



Entscheidungsvariable Δ



$$\Delta = F(x+1, y-1/2)$$

$\Delta < 0 \Rightarrow M$ liegt innerhalb $\Rightarrow$ wähle $(x+1, y)$

$\Delta \geq 0 \Rightarrow M$ liegt außerhalb $\Rightarrow$ wähle $(x+1, y-1)$

Berechnung von Δ

$$\Delta = F(x+1, y-\frac{1}{2}) = (x+1)^2 + (y-\frac{1}{2})^2 - r^2$$

$$\Delta < 0 \Rightarrow$$

$$\Delta' = F(x+2, y-\frac{1}{2}) = (x+2)^2 + (y-\frac{1}{2})^2 - r^2 =$$

$$\Delta + 2x + 3$$

$$\Delta \geq 0 \Rightarrow$$

$$\Delta' = F(x+2, y-\frac{3}{2}) = (x+2)^2 + (y-\frac{3}{2})^2 - r^2 =$$

$$\Delta + 2x - 2y + 5$$

$$\text{Startwert } \Delta = F(1, r-\frac{1}{2}) = 1^2 + (r-\frac{1}{2})^2 - r^2 =$$

$$5/4 - r$$

BresenhamCircle, die 1.

```
x = 0;
y = r;
delta = 5.0/4.0 - r;
while (y >= x) {
    setPixel(x,y);
    if (delta < 0.0) {
        delta = delta + 2*x + 3.0;
        x++;
    }
    else {
        delta = delta + 2*x - 2*y + 5.0;
        x++;
        y--;
    }
}
```

Substitutionen

$$d := \text{delta} - \frac{1}{4}$$

$$dx := 2x + 3$$

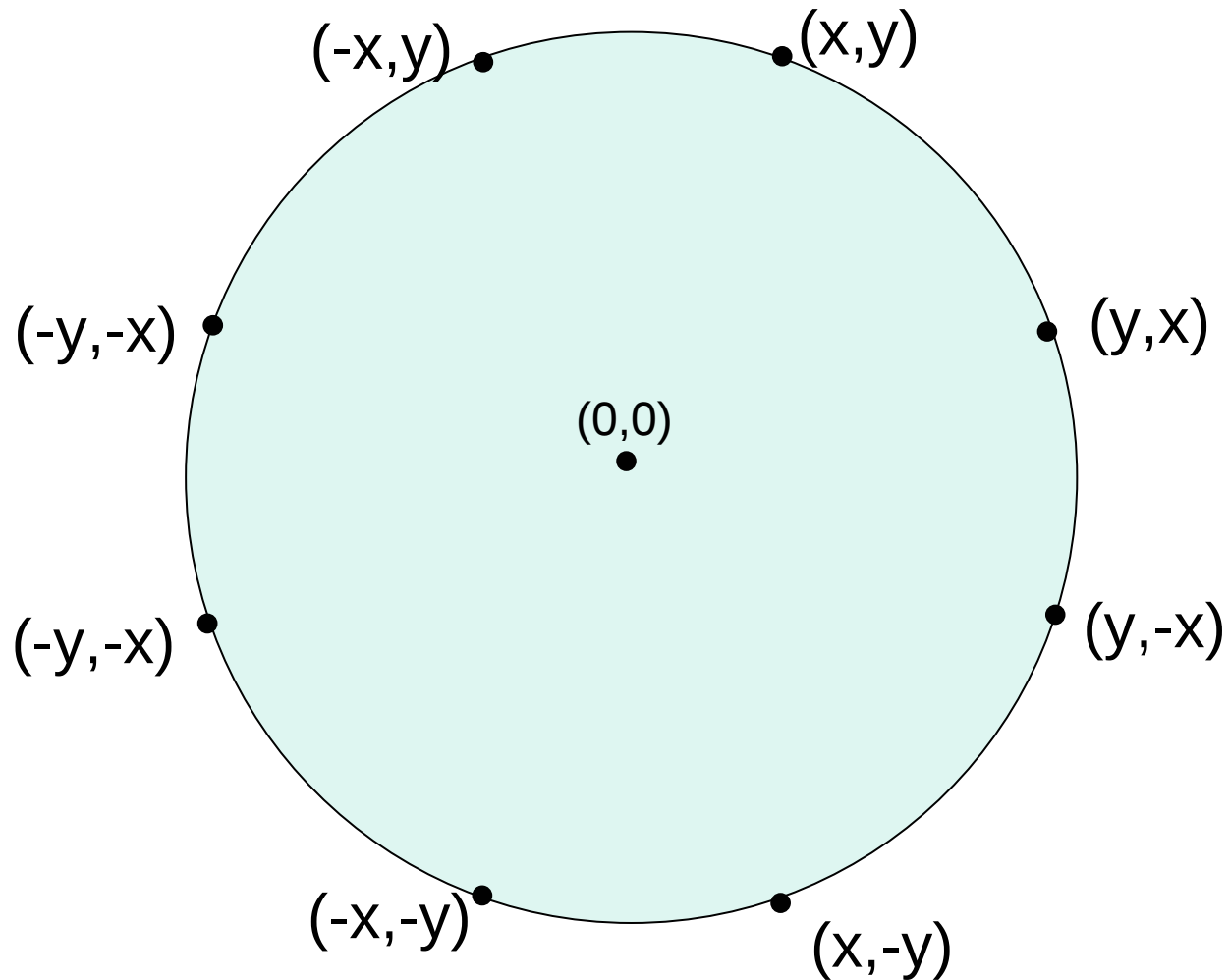
$$dxy := 2x - 2y + 5$$

BresenhamCircle, die 2.

```
x = 0;
y = r;
delta = 5.0/4.0 - r;          d = 1 - r;
                                dx = 3;
                                dxy = -2*r + 5;

while (y >= x) {
    setPixel(x,y);
    if (delta < 0.0) {          (d < 0.0)
        delta = delta + 2*x + 3.0;    d = d + dx;
        x++;                          dx = dx + 2;
    else {                          dxy = dxy + 2;
        delta = delta + 2*x - 2*y + 5.0;    d = d + dxy;
        x++;                          dx = dx + 2;
        y--;                          dxy = dxy + 4;
    }
    }          d:=delta-1/4      dx:=2x+3      dxy:= 2x-2y+5
}
```

Oktanden-Symmetrie



BresenhamCircle, die 3.

```
x=0; y=r; d=1-r; x=3; dx=3; dxy=-2*r+5;
```

```
while (y>=x){
```

```
    setPixel(+x,+y);
```

```
    setPixel(+y,+x);
```

```
    setPixel(+y,-x);
```

```
    setPixel(+x,-y);
```

```
    setPixel(-x,-y);
```

```
    setPixel(-y,-x);
```

```
    setPixel(-y,+x);
```

```
    setPixel(-x,+y);
```

```
    if (d<0) {d=d+dx; dx=dx+2; dxy=dxy+2; x++;}
```

```
    else      {d=d+dxy; dx=dx+2; dxy=dxy+4; x++; y--;}  
}
```

BresenhamCircle

$$\begin{aligned} \text{Zahl der erzeugten Punkte} &= 4 \cdot \sqrt{2} \cdot r \\ &= 10\% \text{ unterhalb von } 2 \cdot \pi \cdot r \end{aligned}$$

Kreis mit Radius r um Mittelpunkt (x,y) :

[~cg/2004/Java/circle/BresenhamCircle.java](#)

Java-Applet:

[~cg/2004/skript/node46.htm](#)

