

Computergrafik SS 2016

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noch Kapitel 3:
2D-Grundlagen

VectorLine

```
int  x1,y1,x2,y2,x,y,dx,dy;
double r, step;

dy = y2-y1;
dx = x2-x1;

step = 1.0/Math.sqrt(dx*dx+dy*dy);
for (r=0.0; r <= 1; r=r+step) {
    x = (int)(x1+r*dx+0.5);
    y = (int)(y1+r*dy+0.5);
    setPixel(x,y);
}
```

StraightLine

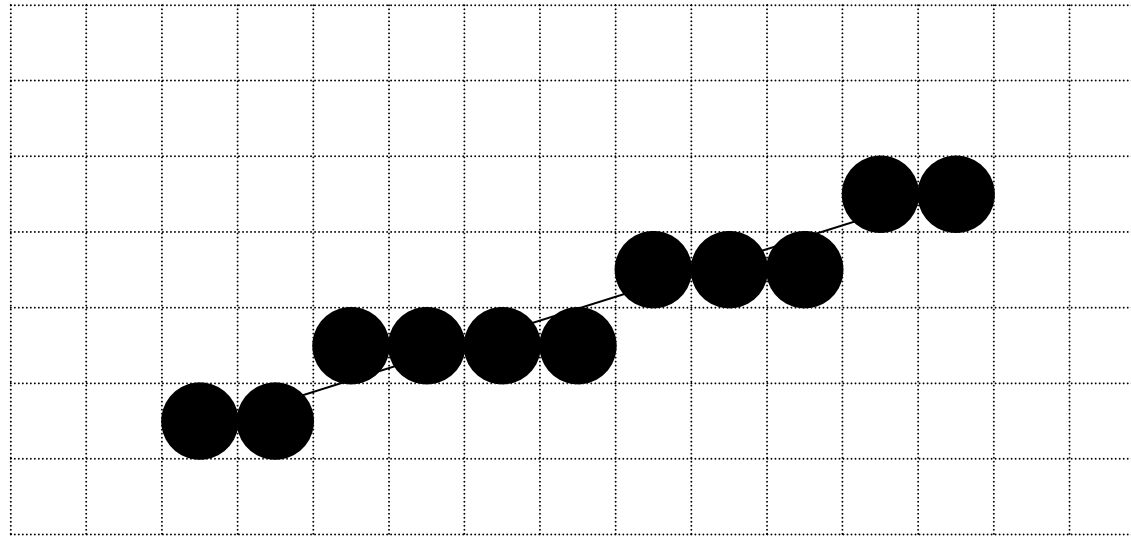
von links nach rechts

```
s = (double)(y2-y1)/(double)(x2-x1);  
c = (double)(x2*y1-x1*y2)/(double)(x2-x1);  
  
for (x=x1; x <= x2; x++) {  
    y = (int)(s*x+c+0.5);  
    setPixel(x,y);  
}
```

Bresenham

Steigung $s = \Delta y / \Delta x$

Fehler $error = y_{ideal} - y_{real}$



BresenhamLine, die 1.

```
dy = y2-y1; dx = x2-x1;
s = (double)dy/(double)dx;
error = 0.0;
x = x1;
y = y1;
while (x <= x2){
    setPixel(x,y);
    x++;
    error = error + s;
    if (error > 0.5) {
        y++;
        error = error - 1.0;
    }
}
```

BresenhamLine, die 2.

```
dy = y2-y1; dx = x2-x1;  
s = (double)dy/(double)dx; delta = 2*dy  
error = 0.0;  
x = x1;  
y = y1;  
while (x <= x2){  
    setPixel(x,y);  
    x++;  
    error = error + delta;  
    if (error > 0.5 > dx) {  
        y++;  
        error = error - 1.0 - 2*dx;  
    }  
    multipliziere Steigung mit 2dx  
}
```

BresenhamLine, die 3.

```
dy = y2-y1; dx = x2-x1;  
s = (double)dy/(double)dx;    delta = 2*dy  
error = 0.0;                  -dx  
x = x1;                          schritt = -2*dx  
y = y1;  
while (x <= x2){  
    setPixel(x,y);  
    x++;  
    error = error + s;          delta  
    if (error > 0.5) {          -dx  
        y++;                     0  
        error = error - 1.0;    - 2*dx  
    }                             + schritt  
}
```

Verschiebe error um dx nach unten. Führe Variable **schritt** ein

Punkt versus Gerade

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \end{pmatrix} + r \cdot \begin{pmatrix} 7-2 \\ 5-3 \end{pmatrix} \quad \vec{u} = \vec{p}_1 + r \cdot \vec{v}$$

$$x = 2 + 5r$$

$$y = 3 + 2r$$

$$2x = 4 + 10r$$

$$5y = 15 + 10r$$

$$- 2x + 5y = 11$$

$$- 2x + 5y - 11 = 0$$

$$F(x,y) = 0 \text{ falls } P \text{ auf der Geraden}$$

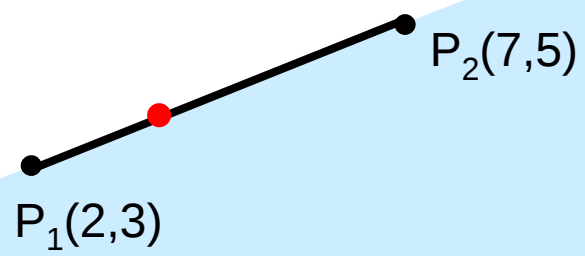
$$> 0 \text{ falls } P \text{ links von der Geraden}$$

$$< 0 \text{ falls } P \text{ rechts von der Geraden}$$

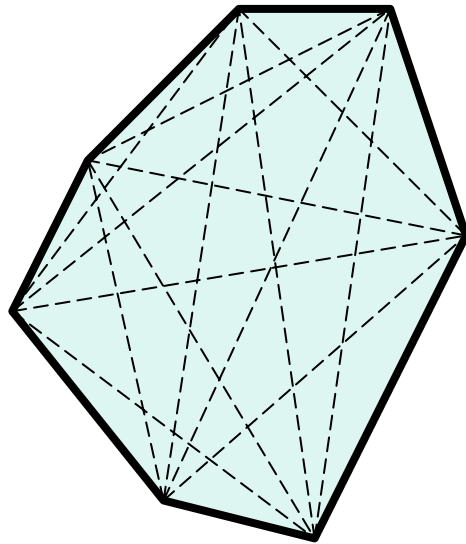
$$\begin{pmatrix} x \\ y \end{pmatrix} \cdot \begin{pmatrix} -2 \\ 5 \end{pmatrix} - 11 = 0$$

Skalarprodukt

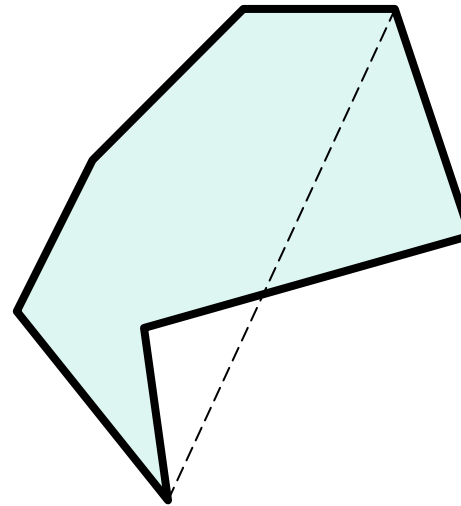
Was hat dieser Vektor
mit der ursprünglichen
Gerade zu tun ?



Polygon

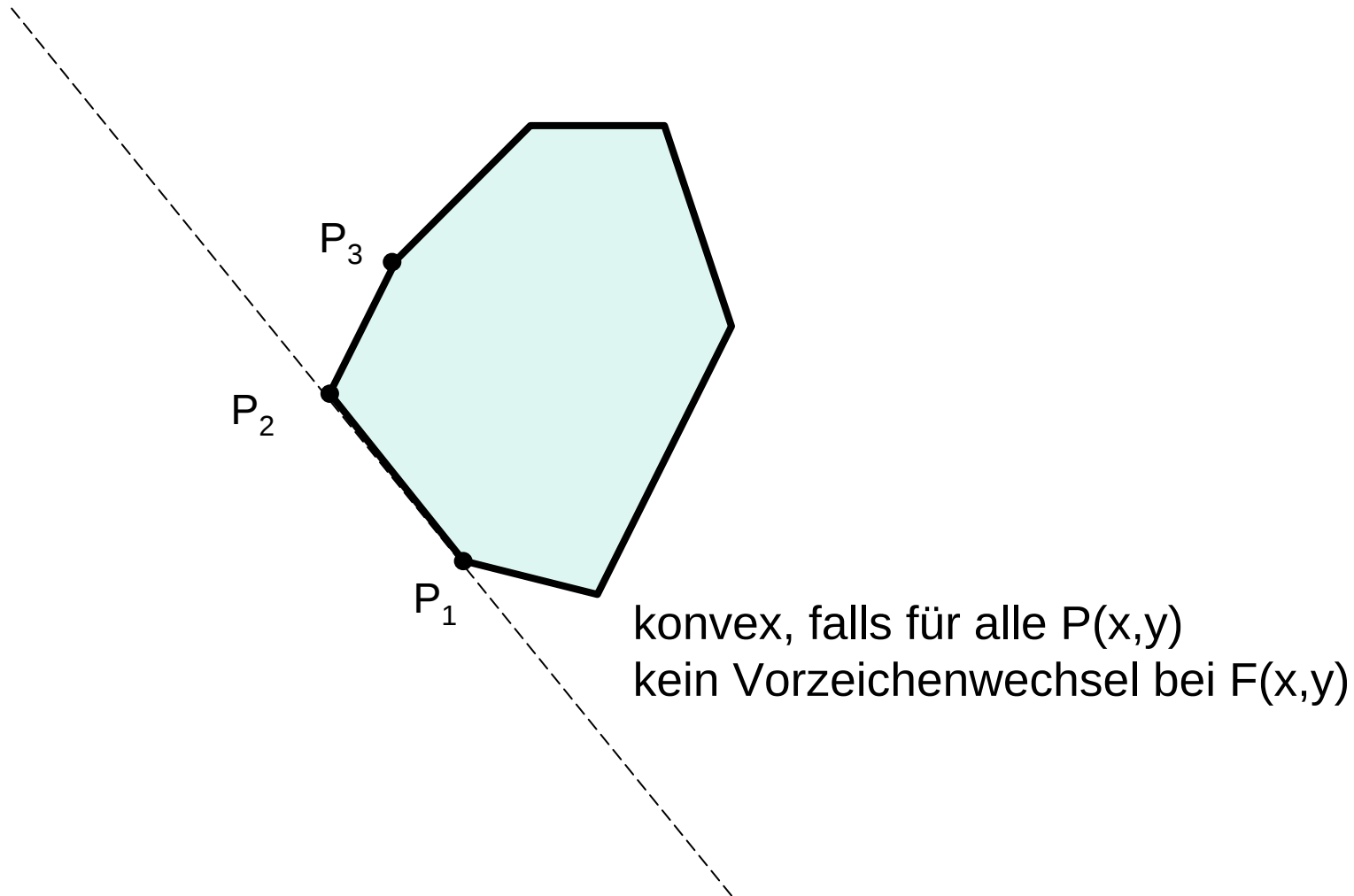


konvex



konkav

Konvexitätstest nach Paul Bourke



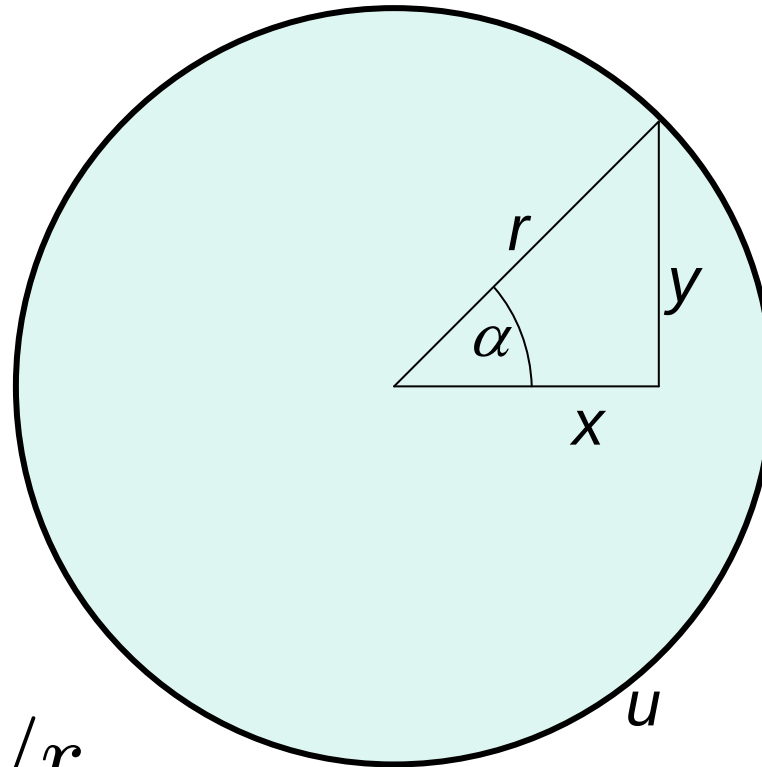
Kreis um (0,0), parametrisiert

$$x = r \cdot \cos(\alpha)$$

$$y = r \cdot \sin(\alpha)$$

$$u = 2 \cdot \pi \cdot r$$

$$step = \frac{2 \cdot \pi}{2 \cdot \pi \cdot r} = 1/r$$

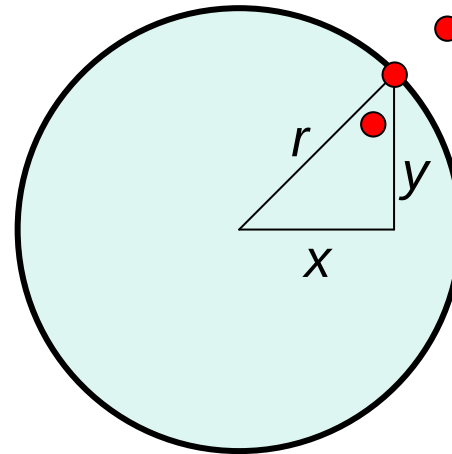


TriCalcCircle

```
double step = 1.0/(double r);  
double winkel;  
  
for (winkel = 0.0;  
     winkel < 2*Math.PI;  
     winkel = winkel+step){  
  
    setPixel((int) r*Math.cos(winkel)+0.5,  
             (int) r*Math.sin(winkel)+0.5);  
}
```

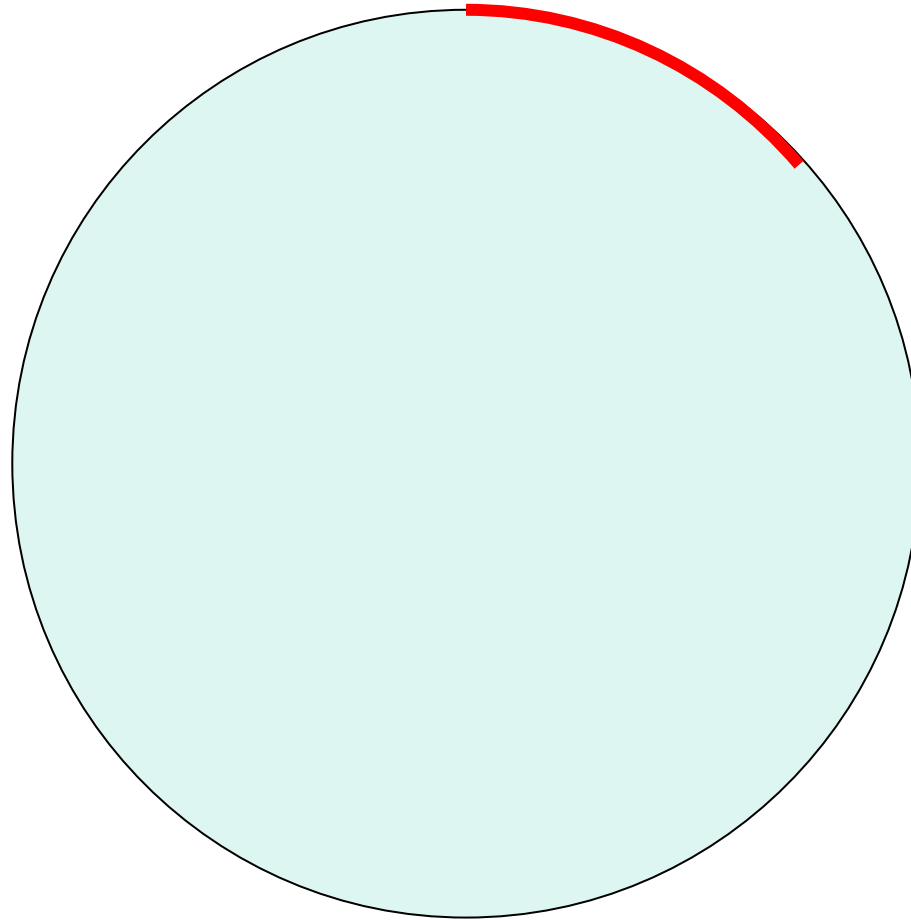
Punkt versus Kreis

$$x^2 + y^2 = r^2$$
$$F(x,y) = x^2 + y^2 - r^2$$

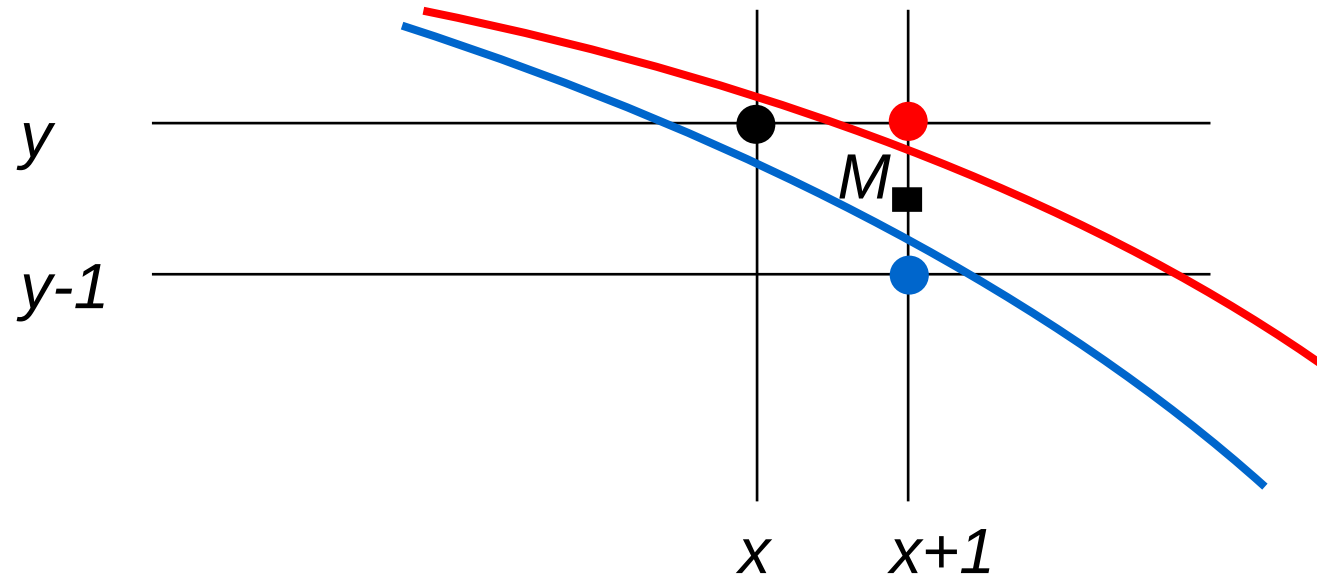


$F(x,y) = 0$ für (x,y) auf dem Kreis
 < 0 für (x,y) innerhalb des Kreises
 > 0 für (x,y) außerhalb des Kreises

Kreis im 2. Oktanden



Entscheidungsvariable Δ



$$\Delta = F(x+1, y^{-1/2})$$

$\Delta < 0 \Rightarrow M$ liegt innerhalb $\Rightarrow$ wähle $(x+1, y)$

$\Delta \geq 0 \Rightarrow M$ liegt außerhalb $\Rightarrow$ wähle $(x+1, y-1)$

Berechnung von Δ

$$\Delta = F(x+1, y-\frac{1}{2}) = (x+1)^2 + (y-\frac{1}{2})^2 - r^2$$

$$\Delta < 0 \Rightarrow$$

$$\Delta' = F(x+2, y-\frac{1}{2}) = (x+2)^2 + (y-\frac{1}{2})^2 - r^2 =$$

$$\Delta + 2x + 3$$

$$\Delta \geq 0 \Rightarrow$$

$$\Delta' = F(x+2, y-\frac{3}{2}) = (x+2)^2 + (y-\frac{3}{2})^2 - r^2 =$$

$$\Delta + 2x - 2y + 5$$

$$\text{Startwert } \Delta = F(1, r-\frac{1}{2}) = 1^2 + (r-\frac{1}{2})^2 - r^2 =$$

$$5/4 - r$$

BresenhamCircle, die 1.

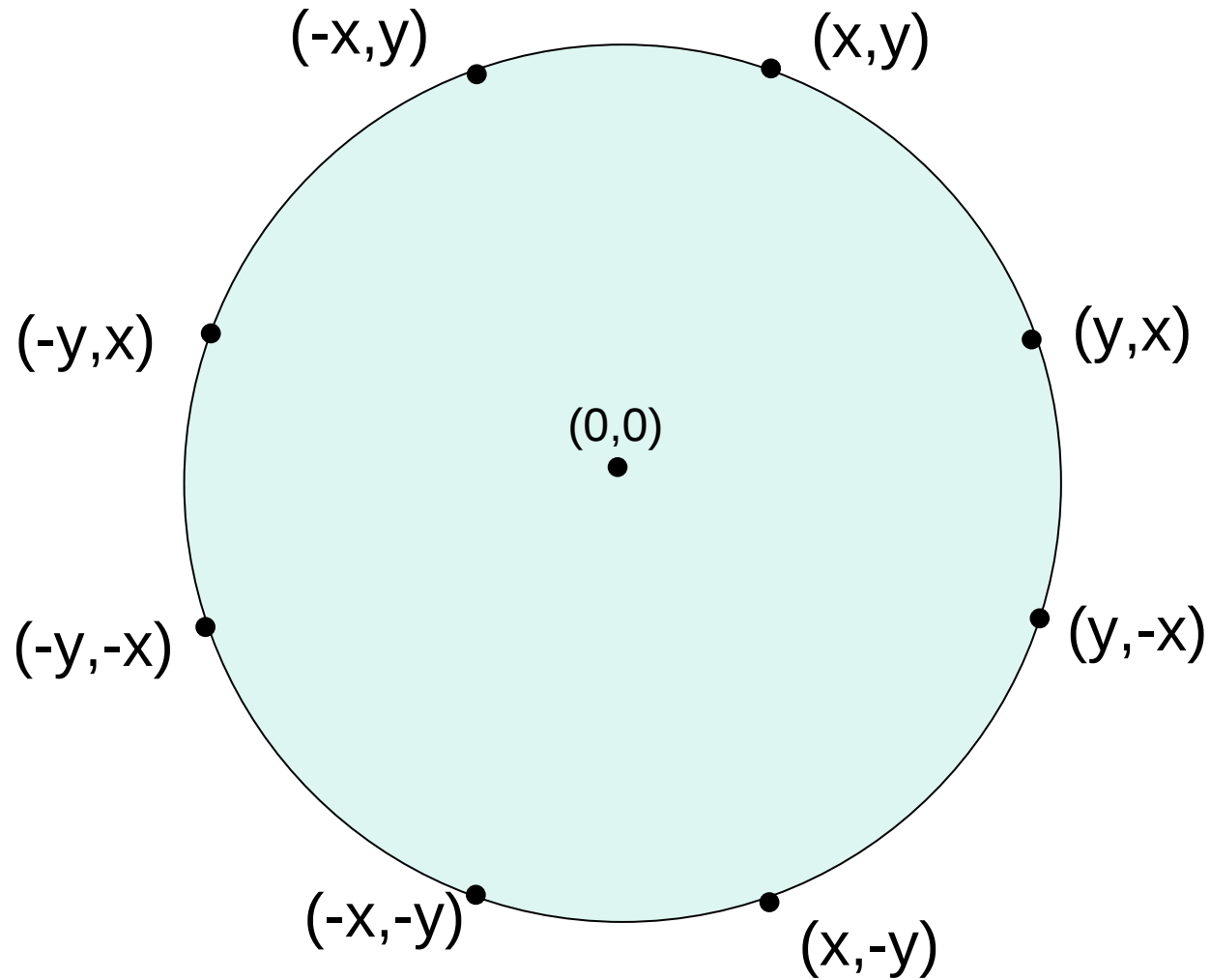
```
x = 0;
y = r;
delta = 5.0/4.0 - r;
while (y >= x) {
    setPixel(x,y);
    if (delta < 0.0) {
        delta = delta + 2*x + 3.0;
        x++;
    }
    else {
        delta = delta + 2*x - 2*y + 5.0;
        x++;
        y--;
    }
}
```

BresenhamCircle, die 2.

```
x = 0;
y = r;
delta = 5.0/4.0 - r;          d = 1 - r;
                                dx = 3;
                                dxy = -2*r + 5;

while (y >= x) {
    setPixel(x,y);
    if (delta < 0.0) {          (d <= 0.0)
        delta = delta + 2*x + 3.0;    d = d + dx;
        x++;                             dx = dx + 2;
    else {                             dxy = dxy + 2;
        delta = delta + 2*x - 2*y + 5.0;    d = d + dxy;
        x++;                             dx = dx + 2;
        y--;                             dxy = dxy + 4;
    }                                     dxy := 2x - 2y + 5
    }                                     d := delta - 1/4    dx := 2x + 3
}
```

Oktanden-Symmetrie



BresenhamCircle, die 3.

```
x=0; y=r; d=1-r; x=3; dx=3; dxy=-2*r+5;
while (y>=x){
    setPixel(+x,+y);
    setPixel(+y,+x);
    setPixel(+y,-x);
    setPixel(+x,-y);
    setPixel(-x,-y);
    setPixel(-y,-x);
    setPixel(-y,+x);
    setPixel(-x,+y);

    if (d<0) {d=d+dx; dx=dx+2; dxy=dxy+2; x++;}
    else    {d=d+dxy; dx=dx+2; dxy=dxy+4; x++;
             y--;}
}
```

Source: ~cg/2016/skript/Sources/drawBresenhamCircle.jav

Java-Applet: ~cg/2016/skript/Applets/2D-basic/App.html

Ellipse um (0,0)

$$(e + x)^2 + y^2 = a_1^2$$

$$(e - x)^2 + y^2 = a_2^2$$

$$2a$$

$$b = \sqrt{a^2 - e^2}$$

